

Dubai Municipality Survey Section

Derivation of Datum Transformation Parameters for Dubai Emirate Between Clark1880 and WGS84 Spheroid

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Why it was necessary ?

- About 9000 control points were available on Clark1880 UTM
- Whole military and border information were on Clark1880
- In the year 1999 DM switch over to WGS84 spheroid and new projection called DLTM was introduced on the same spheroid started connecting old control station Survey section
- Unfortunately for CAD purposes community wise parameters were developed
- There were no single universal parameters for datum transformation available

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Geodetic Datums

Nothing but spheroid of origin

We need

- Spheroid parameter : a, f
- Origin : X_o, Y_o, Z_o
- Orientation of axis : R_x, R_y, R_z

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Type of Geodetic Datum

A local datum is the best fit to the Geoid in a particular region

Local Geodetic Datum (Topocentric)

The global datum is a best fit to the Geoid over the whole earth

Global Geodetic Datum (Geocentric)

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LOCAL DATUM

Local datum are classified as Horizontal and Vertical datum

Horizontal Datum

A horizontal geodetic datum may consist of the longitude and latitude of an initial point (origin); an azimuth of a line (direction) to some other triangulation station; the parameters (radius and flattening) of the ellipsoid selected for the computations; and the geoid separation at the origin

Vertical Datum

Vertical datum provides the reference to measure the height

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Local Datum Definitions in Dubai Emirate

Spheroid : Clark1880

Semi Major Axis (a)	6378249.145
Semi Minor Axis (b)	6356514.870
Flattening (1/f)	293.465

Datum : Nahrwan

Vertical Datum : DMD – Port Rashid Datum

Projection Parameters of Clarke 1880 UTM (Universal Transverse Mercator)

Zone	40
False Northing	0.00
False Easting	500,000 m
Origin Latitude	0.00
Central Meridian (CM)	57 E
Scale Factor on CM	0.9996

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GEOCENTRIC DATUMS

- Their geometrical center corresponds with the Earth's center of mass or geocenter.
- Geocentric datum is one which best approximates the size, shape and Geoid of the earth as a whole.

- 1 The first set of coordinates defined by the Major earth axis :the axis around which the earth is spinning.
- 2 Second axis is: to define by the intersection of circle equatorial plane and the Greenwich meridian.
- 3 The third axis is the plane makes R.H.S. with the two

- Defining the origin for curvilinear coordinates Latitude, Longitude and Height.

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Geocentric coordinates system

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If the earth's spheroid semi major axis is **a**, semi minor axis **b**, and inverse flattening **1/f**, then

$$\begin{aligned} X &= (v + h) \cos \phi \cos \lambda \\ Y &= (v + h) \cos \phi \sin \lambda \\ Z &= (v(1 - e^2) + h) \sin \phi \end{aligned}$$

where v is the prime vertical radius of curvature at latitude ϕ and is equal to

$$v = \frac{a}{\sqrt{1 - e^2 \sin^2 \phi}}$$

$e^2 = (a^2 - b^2)/a^2 = 2f - f^2$ e is the eccentricity of the ellipsoid

Where $h =$ Ellipsoidal Height
 $H =$ Orthometric height,
 $N =$ Geoid-ellipsoid Separation

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ADVANTAGES OF THE GEOCENTRIC DATUM

- A geocentric datum has the center of the earth as its origin
- Supports the latest survey techniques and provides a modern and accessible positioning framework, free of distortion for most practical purposes.
- Provides global integration and supports the direct use of satellite positioning systems such as GPS
- No transformation will be involve
- Easy to establish link with the any international datum
- Spatial data can be used directly by GIS users

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DATUMS AND PARAMETERS USED WORLD WIDE

NAME	SEMI MAJOR AXIS	FLATTENING	WHERE USED
Krassowsky (1940)	6,378,245m	1/298.3	Russia
International (1924)	6,378,388	1/297	Europe
Clarke (1880)	6,378,249	1/293.46	France, Africa, UAE
Clarke (1866)	6,378,206	1/294.98	North America
Bessel (1841)	6,377,397	1/299.15	Japan
Airy (1830)	6,377,563	1/299.32	Great Britain
Everest (1830)	6,377,276	1/300.80	India
WGS 66 (1966)	6,378,145	1/298.25	USA/DoD
GRS 67 (1967)	6,378,160	1/298.25	Australia/Australia
WGS 72 (1972)	6,378,135	1/298.26	USA/DoD
WGS 84 (1984)	6,378,137	1/298.25722	WORLD WIDE

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Brief History

Adoption of Geocentric Datum in Dubai

- Dubai Emirates Survey network control based on Old Trucial Coast Countries 3rd order Geodetic Control on CLARK1880 Ellipsoid, setup during 1927-1931
- 70's developments of Emirates demanded survey control and mapping very extensively which resulting a major observation of survey networks, by Triangulation, traverse and Trilateration. During 1978-80 and subsequent Aerial Photogrammetric mapping in 1983 on Clark1880
- During 1979 using Doppler technique three stations observed on WGS72 Spheroid.
- In the year 1991 the first order Geodetic GPS Network on WGS84 Spheroid was established (using transformation from wgs72 to wgs84). Total 62 monuments were observed.
- 1995 is the year where Dubai adopted ITRF-93 a geocentric datum .A land mark in the history of Survey of Dubai.

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Establishment of Absolute ITRF Station in Dubai

ITRF 93 - GPS NETWORK

- 4 Stations in Dubai (ET228, ET225, BP5, ET145)
- 1 (ET152) In Hatta and 1 in Fujera
- 3 IGS Reference Stations (Graz –Austria, Metera –Italy and Kitab –Uzbekistan)
- Planning and Observation by Institute of applied Geodesy (IfAG) - Germany and DM

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Main Control Network

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Datum transformation problem

- Lack of geoid information
- Non uniformity of control distributions
- Different class of station accuracy
- In homogeneity of control
- For working purposes a Bi-cubic 16 parameter were attempted. They developed a method to estimate the parameters using simple interpolation procedures, but accuracy was in 1 – 3 m range

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Datum Transformation

To transform one datum to another we must know the relationship between the chosen ellipsoids in terms of position and orientation. The relationship is defined by 7 constants.

- o **3 translation** Distance of the ellipsoid center from the center of the earth ($\Delta X, \Delta Y, \Delta Z$)
- o **3 rotations** Rotations around the X, Y, and Z of the Cartesian Coordinate System Axes (ϵ, ψ, ω)
- o **1 scale factor** Scale change (**S**) of the survey control network

Also can work with the following combination

Transformation	TYPE	parameter	Minimum Requirements
2D		2	2 points with position
3D	3 Shifts	3	1 points with position height
3D	3 Shifts+ Scale	4	2 points with position height
3D	3 Shifts + Rotation about Z+ scale	5	2 points with position height
3D	3 Shifts + 3 Rotation + 1 Scale	7	3 points with position height

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Translations (3 Parameters)

Movement of points along an Axis

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Rotations (3 Parameters)

Movement of points around an Axis

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Scale (1 Parameter)

Changing the distance between points

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7 Parameter Transformation between two Datum

$$\begin{bmatrix} X_1 \\ Y_1 \\ Z_1 \end{bmatrix} = \begin{bmatrix} \Delta X \\ \Delta Y \\ \Delta Z \end{bmatrix} + s \begin{bmatrix} 1 & R_z & -R_y \\ -R_z & 1 & R_x \\ R_y & -R_x & 1 \end{bmatrix} \begin{bmatrix} X_2 \\ Y_2 \\ Z_2 \end{bmatrix}$$

X_1, Y_1, Z_1 Cartesian coordinates of Datum 1
 X_2, Y_2, Z_2 Cartesian coordinates of Datum 2
 S The scale difference between the coordinates systems
 $\Delta X, \Delta Y, \Delta Z$ The difference between the centers of the two spheroids
 R_x, R_y, R_z The rotations around the three coordinates axes,

Rotations are positive anticlockwise about the axes of Datum 2 coordinates system when viewing the origin from the positive axes

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Effect of Geoid Information

$$\begin{aligned} X &= (v+h) \cos \phi \cos \lambda \\ Y &= (v+h) \cos \phi \sin \lambda \\ Z &= (v(1-e^2)+h) \sin \phi \end{aligned}$$

where $h=H+N$
If $N=0$, Then $h=H$

$$\begin{aligned} X &= (v+H) \cos \phi \cos \lambda \\ Y &= (v+H) \cos \phi \sin \lambda \\ Z &= (v(1-e^2)+H) \sin \phi \end{aligned}$$

If $N \neq 0$

$$\begin{aligned} \Delta X &= N \cos \phi \cos \lambda \\ \Delta Y &= N \cos \phi \sin \lambda \\ \Delta Z &= (v(1-e^2)+N) \sin \phi \end{aligned}$$

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Comparison of WGS and Clark Spheroid

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The Bursa-Wolf Transformation Model

Is a seven-parameter model for transforming three-dimensional Cartesian coordinates between two datums

The transformation involves three geocentric datum shift parameters ($\Delta X, \Delta Y, \Delta Z$), three rotation elements (R_x, R_y, R_z) and scale factor ($1+\Delta L$).

$$\begin{bmatrix} X_{WGS84} \\ Y_{WGS84} \\ Z_{WGS84} \end{bmatrix} = \begin{bmatrix} \Delta X \\ \Delta Y \\ \Delta Z \end{bmatrix} + \begin{bmatrix} 1+\Delta L & R_z & -R_y \\ -R_z & 1+\Delta L & R_x \\ R_y & -R_x & 1+\Delta L \end{bmatrix} \begin{bmatrix} X_{CLK} \\ Y_{CLK} \\ Z_{CLK} \end{bmatrix}$$

$X_{WGS84}, Y_{WGS84}, Z_{WGS84}$: are the global datum (WGS84) Cartesian co-ordinates;
 $X_{CLK}, Y_{CLK}, Z_{CLK}$: are the local datum (CLARK) Cartesian co-ordinates.

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The Molodensky-Badekas Transformation Model

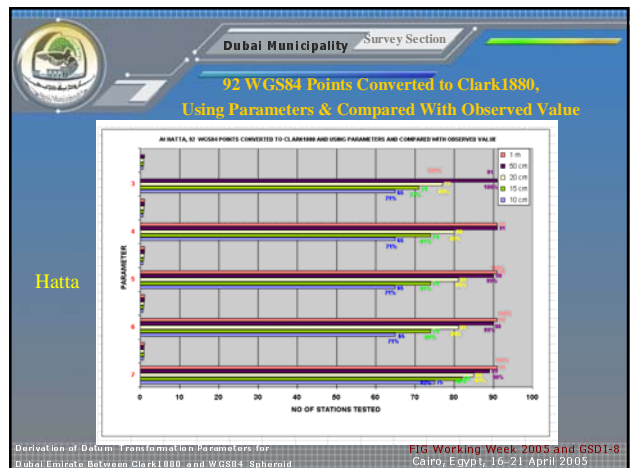
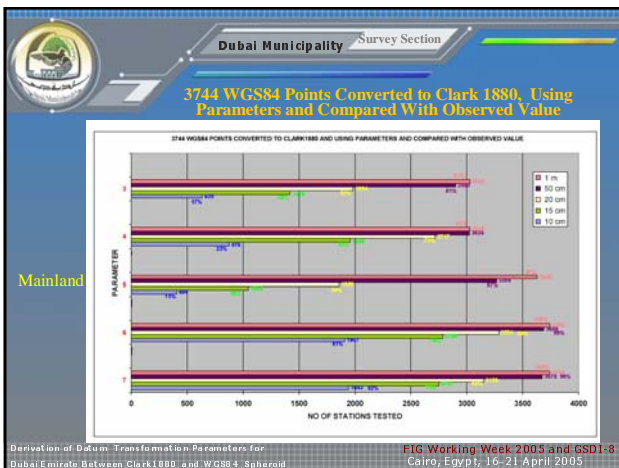
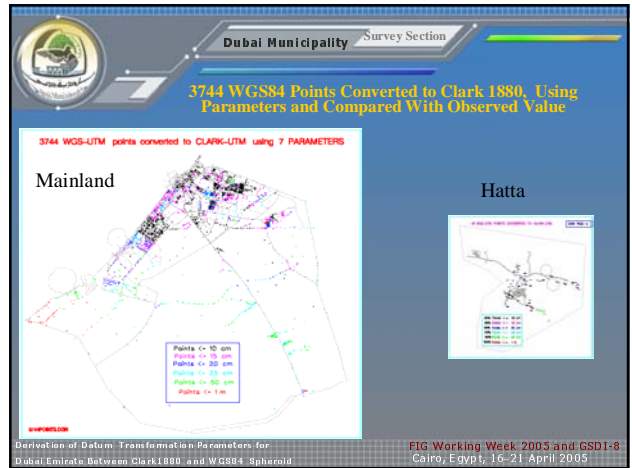
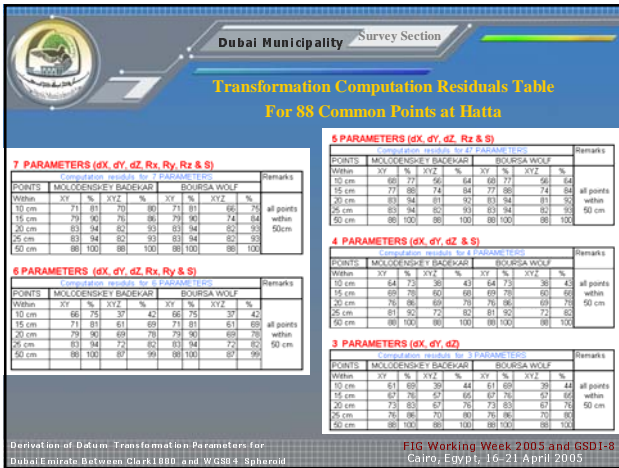
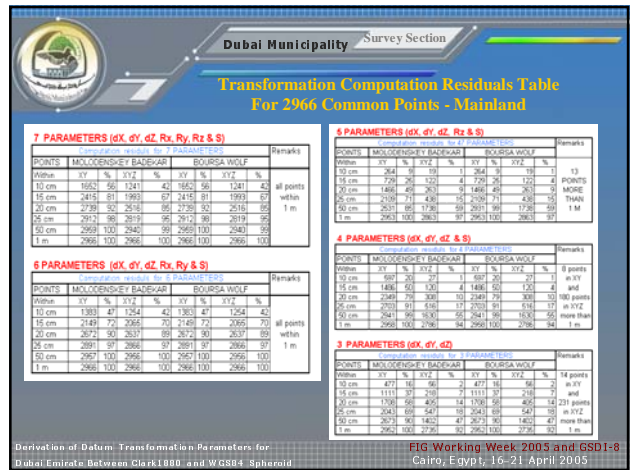
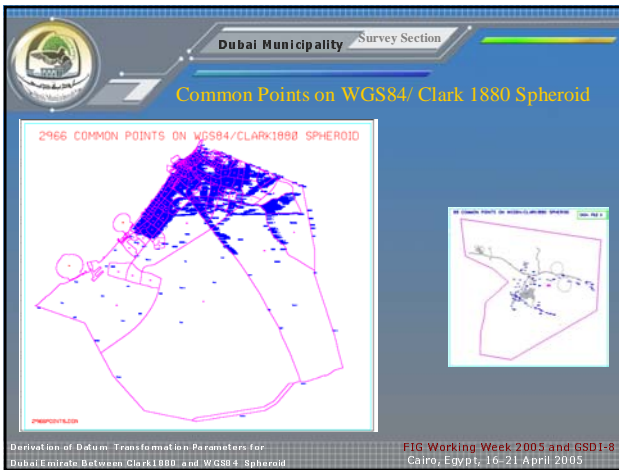
Is also a seven-parameter model for transforming three-dimensional Cartesian coordinates between two datums. The transformation also involves three geocentric datum shift parameters ($\Delta X, \Delta Y, \Delta Z$), three rotation elements (R_x, R_y, R_z) and scale factor ($1+\Delta L$).

$$\begin{bmatrix} X_{WGS84} \\ Y_{WGS84} \\ Z_{WGS84} \end{bmatrix} = \begin{bmatrix} dX \\ dY \\ dZ \end{bmatrix} + \begin{bmatrix} X_m \\ Y_m \\ Z_m \end{bmatrix} + \begin{bmatrix} 1+\Delta L & R_z & -R_y \\ -R_z & 1+\Delta L & R_x \\ R_y & -R_x & 1+\Delta L \end{bmatrix} \begin{bmatrix} X_{clk} - X_m \\ Y_{clk} - Y_m \\ Z_{clk} - Z_m \end{bmatrix}$$

Where $X_m = \frac{1}{n} \sum X_i$, $Y_m = \frac{1}{n} \sum Y_i$, $Z_m = \frac{1}{n} \sum Z_i$
 X_i, Y_i, Z_i : are the Cartesian co-ordinates in the local Clark system;
 n : is the number of common points.

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Accuracy after Transformation using the Transformation Parameters

Accuracy after transformation using the Transformation Parameters Mainland

7 PARAMETERS (dX, dY, dZ, Rx, Ry, Rz & S)

POINTS	MOLODENSKY BADEKAS				BURSA WOLF				Remarks
	XY	%	XYZ	%	XY	%	XYZ	%	
Within	1943	62	1654	44	1944	52	1654	44	34 points
10 cm	2253	73	2527	67	2253	74	2527	67	
20 cm	3150	84	3006	80	3157	84	3006	80	
25 cm	3443	92	3317	89	3451	92	3317	89	
50 cm	3675	96	3676	96	3683	96	3676	96	
1 m	3744	100	3744	100	3744	100	3744	100	

Accuracy after transformation using the Transformation Parameters Hatta

7 PARAMETERS (dX, dY, dZ, Rx, Ry, Rz & S)

POINTS	MOLODENSKY BADEKAS				BURSA WOLF				Remarks
	XY	%	XYZ	%	XY	%	XYZ	%	
Within	75	82	70	77	75	82	70	77	1 point
10 cm	82	90	80	88	82	90	80	88	
20 cm	86	93	84	92	86	93	84	92	
25 cm	86	93	84	92	86	93	84	92	
50 cm	89	96	89	96	89	96	89	96	
1 m	91	100	91	100	91	100	91	100	

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Statistical Quantities for 7 Parameters (Molodensky-Badekas & Bursa-Wolf) Mainland

TABLE FOR STATISTICAL QUANTITIES FOR SEVEN PARAMETER (Molodensky Badekas and Bursa Wolf) Mainland

Mean of the coordinates difference	Standard deviation	Mean Square error
$d\bar{X} = \frac{1}{n} \sum dX_i = \frac{137.5}{3744} = +0.037$	$\sigma_{dX} = \sqrt{\frac{1}{n-1} \sum (dX_i - d\bar{X})^2} = \sqrt{\frac{80.06}{3743}} = +0.146$	$m_{dX} = \sqrt{\frac{1}{n} \sum (dX_i - d\bar{X})^2} = +0.146$
$d\bar{Y} = \frac{1}{n} \sum dY_i = \frac{16.11}{3744} = +0.004$	$\sigma_{dY} = \sqrt{\frac{1}{n-1} \sum (dY_i - d\bar{Y})^2} = \sqrt{\frac{34.002}{3743}} = +0.095$	$m_{dY} = \sqrt{\frac{1}{n} \sum (dY_i - d\bar{Y})^2} = +0.095$
$d\bar{Z} = \frac{1}{n} \sum dZ_i = \frac{-92.4}{3744} = -0.025$	$\sigma_{dZ} = \sqrt{\frac{1}{n-1} \sum (dZ_i - d\bar{Z})^2} = \sqrt{\frac{191.696}{3743}} = +0.226$	$m_{dZ} = \sqrt{\frac{1}{n} \sum (dZ_i - d\bar{Z})^2} = +0.226$

The Vector representing the total root mean square error in XYZ

$$= \sqrt{\frac{1}{n} \sum (dX_i - d\bar{X})^2 + (dY_i - d\bar{Y})^2 + (dZ_i - d\bar{Z})^2} = +0.265$$

NOTE: 1. Total number of points 3744
2. Statistical quantities are calculated only for 7 parameter, which has chosen as final parameters.

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Statistical Quantities for 7 Parameters (Molodensky-Badekas & Bursa-Wolf) Hatta

TABLE FOR STATISTICAL QUANTITIES FOR SEVEN PARAMETER (Molodensky Badekas and Bursa Wolf) HATTA

Mean of the coordinates difference	Standard deviation	Mean Square error
$d\bar{X} = \frac{1}{n} \sum dX_i = \frac{-0.001}{91} = -0.0007$	$\sigma_{dX} = \sqrt{\frac{1}{n-1} \sum (dX_i - d\bar{X})^2} = \sqrt{\frac{0.3362}{90}} = +0.061$	$m_{dX} = \sqrt{\frac{1}{n} \sum (dX_i - d\bar{X})^2} = +0.060$
$d\bar{Y} = \frac{1}{n} \sum dY_i = \frac{-1.95}{91} = -0.013$	$\sigma_{dY} = \sqrt{\frac{1}{n-1} \sum (dY_i - d\bar{Y})^2} = \sqrt{\frac{1.5998}{90}} = +0.129$	$m_{dY} = \sqrt{\frac{1}{n} \sum (dY_i - d\bar{Y})^2} = +0.126$
$d\bar{Z} = \frac{1}{n} \sum dZ_i = \frac{0.09}{91} = +0.001$	$\sigma_{dZ} = \sqrt{\frac{1}{n-1} \sum (dZ_i - d\bar{Z})^2} = \sqrt{\frac{0.2999}{90}} = +0.066$	$m_{dZ} = \sqrt{\frac{1}{n} \sum (dZ_i - d\bar{Z})^2} = +0.066$

The Vector representing the total root mean square error in XYZ

$$= \sqrt{\frac{1}{n} \sum (dX_i - d\bar{X})^2 + (dY_i - d\bar{Y})^2 + (dZ_i - d\bar{Z})^2} = +0.158$$

NOTE: 1. Total number of points 91
2. Statistical quantities are calculated only for 7 parameter, which has chosen as final parameters.

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7 Transformation Parameters

7 (dX, dY, dZ, Rx, Ry, Rz & S) TRANSFORMATION PARAMETERS - Mainland						
	Molodensky Badekas			Bursa Wolf		
	Value	RMS	Unit	Value	RMS	Unit
Shift dX	233.45100	0.0064	m	Shift dX	114.64340	0.9711 m
Shift dY	131.69530	0.0064	m	Shift dY	79.36610	1.1391 m
Shift dZ	-395.81930	0.0064	m	Shift dZ	117.06630	1.5105 m
Rotation about RX	11.83749	0.04628	"	Rotation about RX	11.83749	0.04628 "
Rotation about RY	-11.97969	0.03559	"	Rotation about RY	-11.97969	0.03559 "
Rotation about RZ	0.97067	0.03373	"	Rotation about RZ	0.97067	0.03373 "
Scale	-18.36660	0.1352	ppm	Scale	-18.36660	0.1352 ppm
Rotation Origin (m)	X0=3283896.0005	Y0=4749903.6592	Z0=2699186.5371			

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7 Transformation Parameters

7 (dX, dY, dZ, Rx, Ry, Rz & S) TRANSFORMATION PARAMETERS - Hatta						
	Molodensky Badekas			Bursa Wolf		
	Value	RMS	Unit	Value	RMS	Unit
Shift dX	229.18130	0.0095	m	Shift dX	459.70430	21.1733 m
Shift dY	124.69640	0.0095	m	Shift dY	-12.33080	25.3213 m
Shift dZ	-396.94260	0.0095	m	Shift dZ	-182.51510	38.3242 m
Rotation about RX	4.74440	1.20432	"	Rotation about RX	4.74440	1.20432 "
Rotation about RY	-3.69462	0.69563	"	Rotation about RY	-3.69462	0.69563 "
Rotation about RZ	-9.80796	0.69953	"	Rotation about RZ	-9.80796	0.69953 "
Scale	-16.10110	2.9833	ppm	Scale	-16.10110	2.9833 ppm
Rotation Origin (m)	X0 = 3227836.4629	Y0 = 4810942.429	Z0 = 2659452.6943			

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Transformation Program Flow Chart

DATUM (World Geodetic System 1984)

DLTM Coordinates (Northing, Easting, Height)

↓ Conversion

UTM Coordinates (Northing, Easting, Height)

↓ Conversion

Geographic Coordinates (Latitude, Longitude, Height)

↓ Conversion

Cartesian Coordinates (X, Y, Z)

DATUM (Clarke 1980)

UTM Clarke Coordinates (Northing, Easting, Height)

↓ Conversion

Geographic Coordinates (Latitude, Longitude, Height)

↓ Conversion

Cartesian Coordinates (X, Y, Z)

Molodensky-Badekas & Bursa-Wolf 7 Parameters

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