



FIG Working Week 2016

CHRISTCHURCH, NEW ZEALAND 2-6 MAY 2016

Recovery

from disaster

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Validation of GNSS-based high-precision velocity estimation for outdoor sports

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Introduction

- Outdoor **sports** and **surveying** are faced to **similar challenges**
 - precise timing
 - positioning
 - velocity estimation
- In sports were the **path length** is **equal** for each athlete **velocity** is usually determined using **photocells** systems
- Trajectory and instantaneous velocity are necessary for **performance analysis** and **research**



<http://www.leica-geosystem.com>



<http://www.all-athletics.com/>

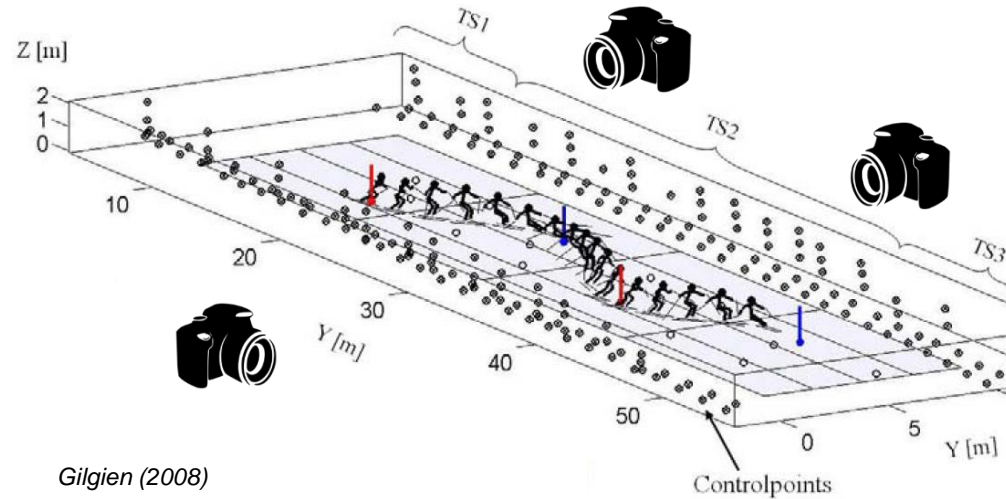


<http://www.live-production.tv/>



Introduction

- **Photogrammetric systems** are applied to reconstruct the body dynamic.
- Sports over large spatial volumes apply **GNSS**
- Goal: **assessment of the accuracy of velocity GNSS measurement**



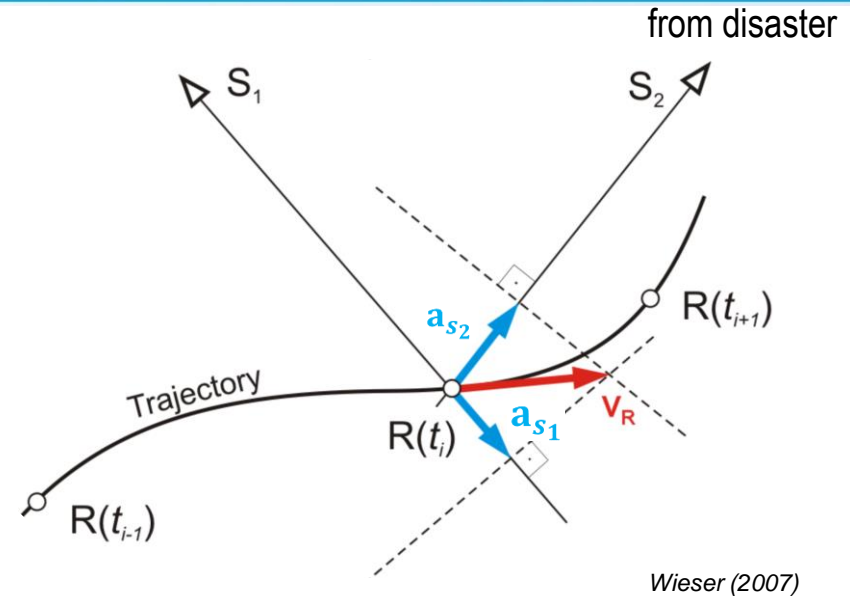
Gilgien (2008)





GNSS velocity computation

- The Doppler shift f_d of the GNSS signals is proportional to the relative velocity between satellite \mathbf{v}_s and receiver \mathbf{v}_r
- Highly precise Doppler observables are obtained as time-derivative of the carrier phase Φ
- The observations are processed kinematically in an Extended Kalman Filter (EKF) using a MATLAB-based GNSS post-processing software.



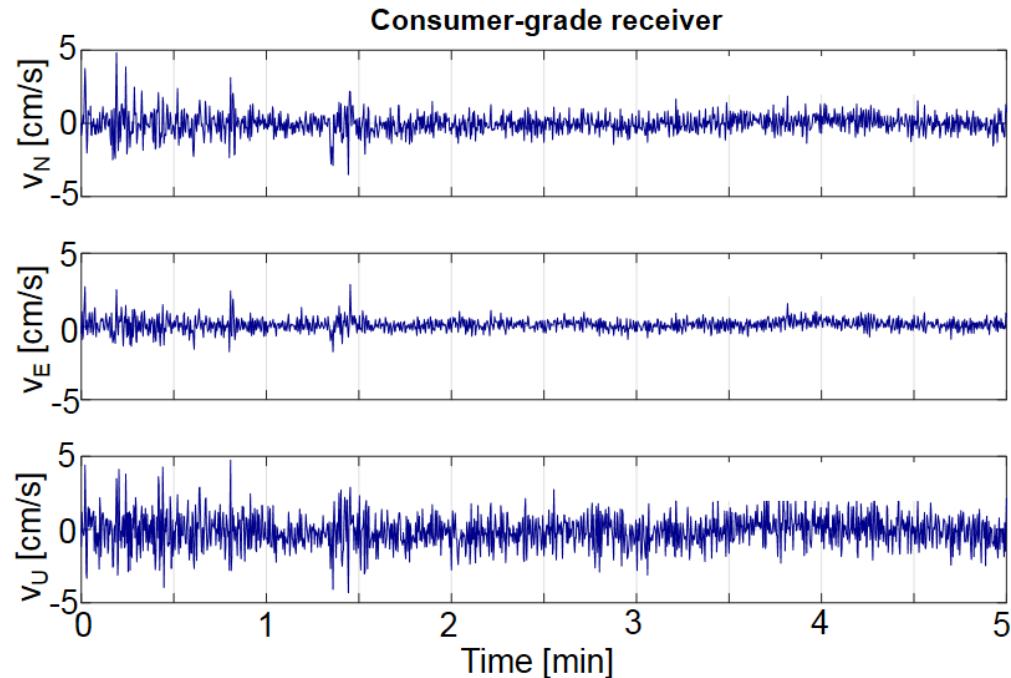
$$f_d(t_i) := \frac{\Phi(t_{i+1}) - \Phi(t_{i-1})}{2\Delta t} \approx f_0 \cdot \frac{v(t_i)}{c}$$

$$f_d^{obs} - f_d^{sat} = \frac{1}{\lambda} \mathbf{a}^T \mathbf{v}_r - f_0 \dot{b}_r + \varepsilon$$



GNSS velocity computation

- Many effects will affect a static receiver like a kinematic one
- The level of random observation noise is expected to be higher
- Static test as an indication of the accuracy



	σ_v [mm/s]
Geodetic receiver	3.5
Consumer-grade receiver	8.5

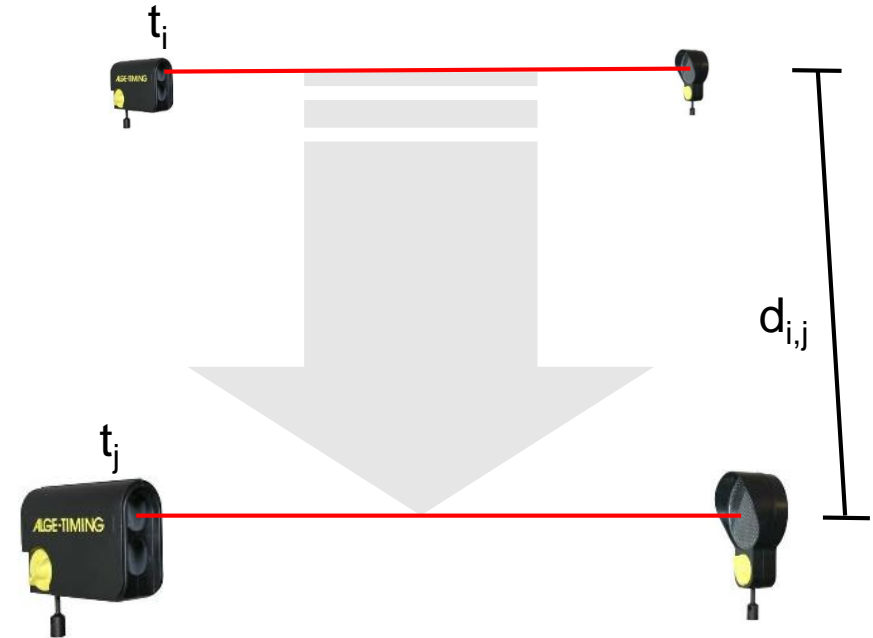
$$\sigma_{\bar{v},G} = \frac{1}{\sqrt{n}} \sigma_v$$



from disaster

Reference system

- Photocells as reference measurements for the experimental investigation

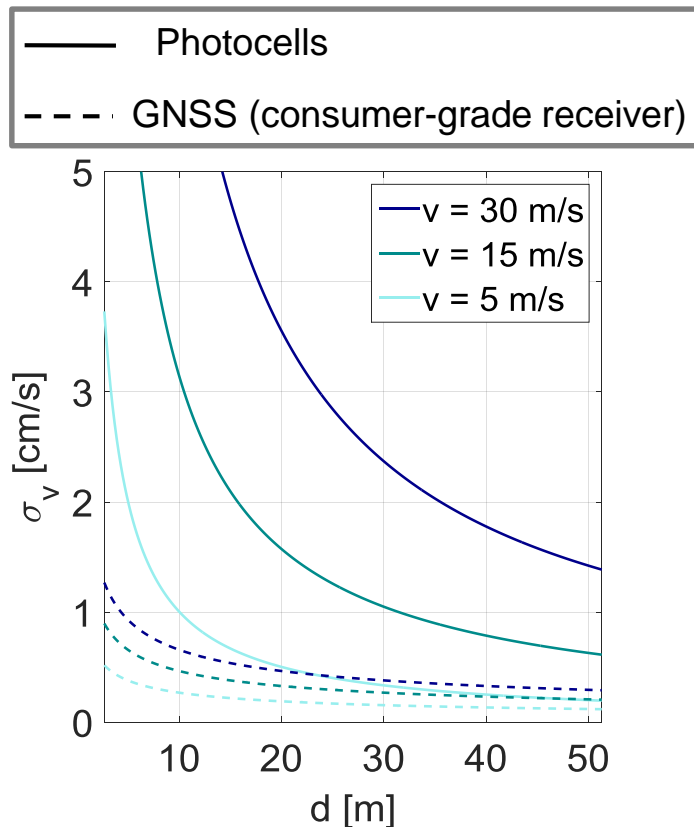


$$\bar{v}_{i,j}^p = \frac{d_{i,j}}{(t_j - t_i)}$$

$$\sigma_{\bar{v}_{i,j}^p} = \sqrt{\left(\frac{\partial \bar{v}_{i,j}^p}{\partial t_i}\right)^2 \cdot \sigma_{t_i}^2 + \left(\frac{\partial \bar{v}_{i,j}^p}{\partial t_j}\right)^2 \cdot \sigma_{t_j}^2 + \left(\frac{\partial \bar{v}_{i,j}^p}{\partial d_{i,j}}\right)^2 \cdot \sigma_{d_{i,j}}^2} = \frac{\bar{v}_{i,j}^p}{d_{i,j}} \sqrt{2 \cdot (\bar{v}_{i,j}^p \sigma_t)^2 + \sigma_{d_{i,j}}^2}$$



Comparison between the velocities estimated using GNSS and photocells

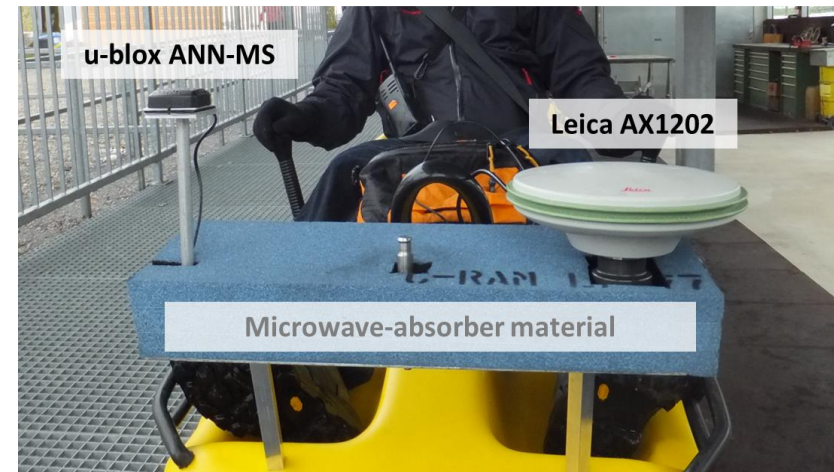


- Additional requirements:
 - The travelled distance with an accuracy of a few cm
 - Stable relation between the GNSS antenna and the part triggering the photocells
 - Repeatable experiment
 - Representative dynamic for outdoor sports (e.g. alpine skiing)



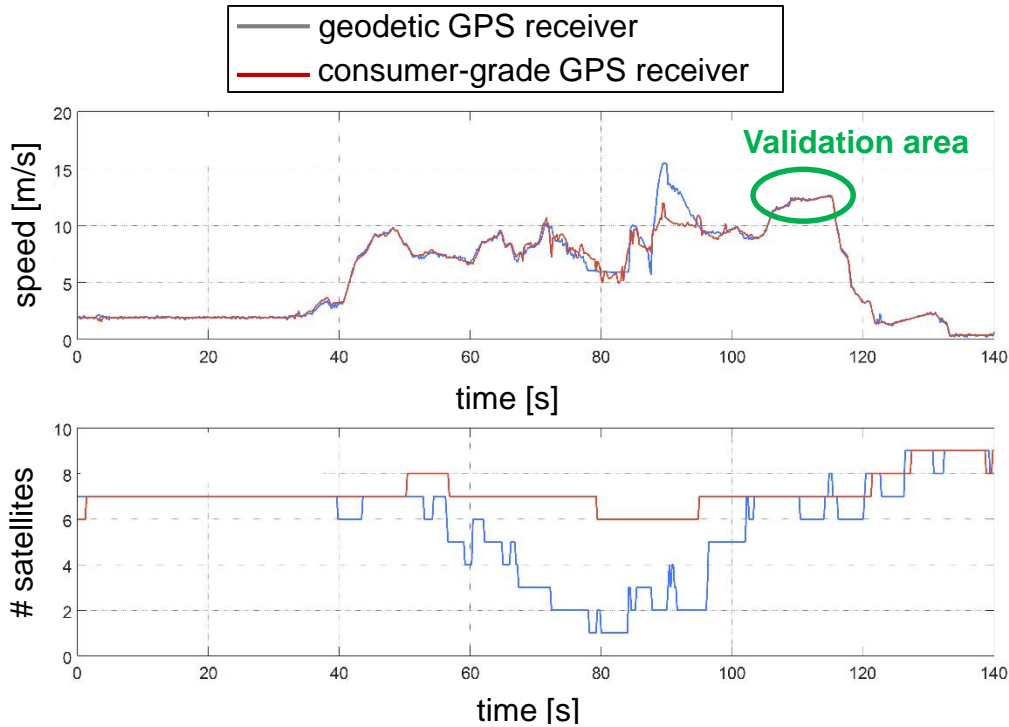
Kinematic test measurements

- 51.2 m, equipped with 9 photocells
- Distances between the photocells intervals from 3 m to 12 m
- 6 runs with average velocities varying from 45 km/h to 55 km/h
- 2 GNSS equipment
 - A geodetic GNSS receiver (Leica 1200) and antenna (Leica AS10)
 - A consumer-grade GNSS receiver (ublox EVK6T) and antenna (ANN-MS)





Results and discussion



Geodetic receiver:

- optimized for quality

Consumer-grade receiver:

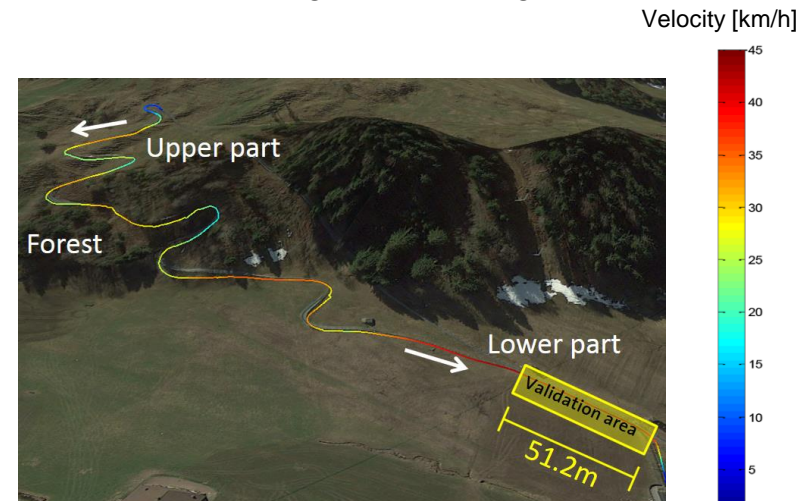
- fast signal acquisition
- tracking of weak signals

(i) ascent

(ii) upper part

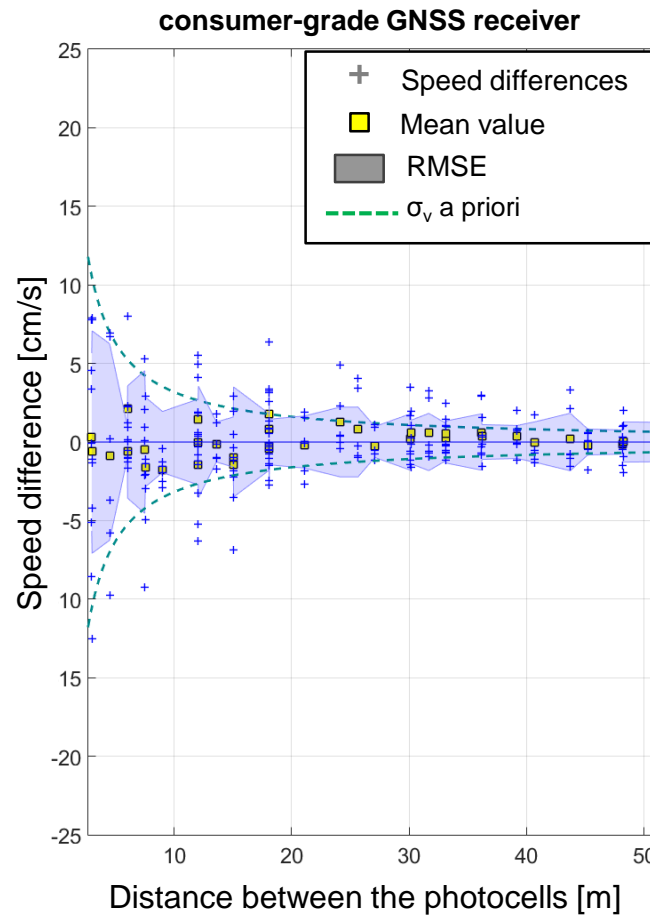
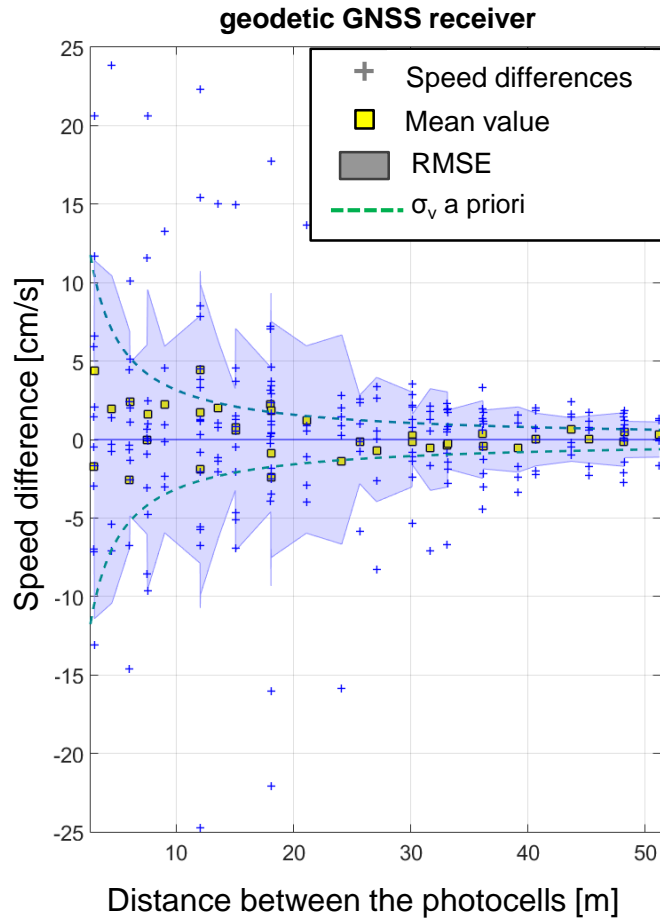
(iii) forest

(iv) lower part (validation)





Results and discussion





Conclusion

- Development of a method to **predict accuracies** for **velocity measurement** using GNSS and photocells
- An **empirical test** measurement on a **coaster track** compared both velocity measurement systems
- A precision better than **10 mm/s** can be obtained for the velocity estimated using a consumer-grade GNSS equipment



Swiss Reception

Come along, have a drink, and win attractive prices!!!

Thursday, 5 May,
5pm-6pm
at "Lot 55 Café"

