



Volunteering for the future – Geospatial excellence for a better living

Validation of UWM new global ionosphere model during the most severe geomagnetic storm of the year 2018

Paweł Wielgosz, Anna Krypiak-Gregorczyk, Wojciech Jarmołowski, Beata Milanowska

University of Warmia and Mazury in Olsztyn, Poland













Introduction

- The ionosphere is still considered as the main source of errors in precise positioning, which is affecting surveying and geodetic applications.
- Currently, seven IGS Ionosphere Associate Analysis Centers (IAACs) independently produce Global Ionosphere Maps (GIMs) with the use of various methods.
- There are several studies investigating the quality of the IAAC maps,
 the recent one by Roma-Dollase et al. (2018), and also by Wielgosz et al. (2021)
- In this presentation we verified the accuracy of the new UWMG ionosphere model under various geomagnetic conditions (by comparing to the best available GIMs).
- The study is based on GIM self-consistency analysis and comparisons to altimetry-derived VTEC.

Roma-Dollase et al. (2018) Consistency of seven different GNSS global ionospheric mapping techniques during one solar cycle. J Geod 92(6):691-706. DOI: 10.1007/s00190-017-1088-9 Wielgosz et al. (2021) Validation of GNSS-derived global ionosphere maps for different solar activity levels: case studies for years 2014 and 2018. GPS Solutions 25, 103. DOI: 10.1007/s10291-021-01142-x









Analyzed Global Ionosophere Maps (GIMs)

GIM ID	Method	Shell model	Time resolution
IGSG	Weighted mean	Combined	2 h
CODG	Spherical harmonics	Modified single-layer	1 h
UQRG*	Tomographic with kriging	Multi-layer	15 min
UWMG-t1*	Spherical harmonics Thin-plate smoothing spline	Modified single-layer	1 h

* not official IGS product









Volunteering for the future – Geospatial excellence for a better living

Observational data and tested period

- L1&L2 carrier phase data from ~273 GNSS stations
- dual-frequency carrier phase and pseudorange GPS + GLONASS data
- sampling interval: 30 seconds.
- elevation cut-off: 10°



test period:

• 23-29.08.2018 (235-241/2018)













Volunteering for the future -Geospatial excellence for a better living







Volunteering for the future – Geospatial excellence for a better living

Trimble



PLATINUM SPONSOR





Volunteering for the future – Geospatial excellence for a better living

Trimble



PLATINUM SPONSOR:

Analyzed Global Ionosophere Maps (GIMs)





ORG ANISED BY

XXVII FIG CONGRESS 11–15 SEPTEMBER 2022 Warsaw, Poland

Self-consistency analysis

Our approach is based on:

- 1. Calculation of geometry free L_I of carrier phase observations for a continuous arc (elevation cut-off 20 degrees).
- 2. Calculation of STEC for the same satellite arc, but from given GIMs (GIM-STEC).
- 3. Fitting L_1 into GIM-STEC (removing L_1 bias).
- 4. Residual analysis (see in. Krypiak-Gregorczyk et al. 2017, Remote Sens 9 (12):1221. DOI: 10.3390/rs9121221





Volunteering for the future – Geospatial excellence for a better living

Self-consistency analysis

GNSS Test data from 23 globally distributed stations



Longitude









Volunteering for the future -Geospatial excellence for a better living

A. GNSS STEC & GIM STEC **B. RESIDUALS Self-consistency analysis** 23 3 21 STEC [TECU] 12 12 12 STEC [TECU] 2 Station: KATO IGSG **Year:** 2018 **DOY:** 238 -2 13 -3 **PRN:** 19 11 16 17 18 19 16 17 18 15 15 19 GPST [hour] GPST [hour] 23 3 21 [19 17 17 15 2 STEC [TECU] UWMG-t1 -2 13 -3 11 -4 18 19 18 19 15 16 17 15 16 17 GPST [hour] GPST [hour]







esr





A. GNSS STEC & GIM STEC

Volunteering for the future -Geospatial excellence for a better living

Self-consistency analysis

CODG CODG 23 21 STEC [TECU] 12 12 12 STEC [TECU] CODG 13 -3 11 -4 16 18 19 16 15 17 15 GPST [hour] GPST [hour] UQRG UQRG 23 3 21 STEC [TECU] 12 12 12 STEC [TECU] UQRG 13 -3 11└ 15 -4 18 16 17 19 15 16 GPST [hour] GPST [hour]



Station: KATO

Year: 2018

DOY: 238

PRN: 19





19

B. RESIDUALS

17

17

18

18

19





Volunteering for the future – Geospatial excellence for a better living

Self-consistency analysis



Daily RMS distribution for all analysed GIMs [TECU]









Volunteering for the future – Geospatial excellence for a better living

Self-consistency analysis



Average RMS in low-, mid- and high-latitude regions for selected GIMs (235-241 DOY/2018)









Volunteering for the future – Geospatial excellence for a better living









Trimble



Volunteering for the future – Geospatial excellence for a better living

Validation by altimetry



Daily STD distribution based on the comparison with Jason-3 data for all analysed GIMs











Volunteering for the future – Geospatial excellence for a better living

Validation by altimetry



Daily STD distribution based on the comparison with Sentinel-3A data for all analysed GIMs









Volunteering for the future – Geospatial excellence for a better living

Summary of the results

Overall RMS from self-consistency tests

Overall STD from comparisons to altimetry from Jason-3 and Sentinel3A











Conclusions

- The self-consistency RMS for all tested GIMs varies from 1.17 TECU to 1.51 TECU, with an RMS value for UWM of 1.18 TECU.
- STDs from altimetry comparisons vary from 1.83 TECU (UQRG, Jason-3) to 2.77 TECU (UWMG-t1, Sentinel-3A).
- UWMG-t1 has the best accuracy in the high and mid latitude regions, while in low latitude regions the accuracy of the UWMG-t1 is slightly lower than UQRG.
- The accuracy of the UWMG-t1 model is the lowest for ocean regions with less data availability which indicates the need to complete the measurement data set.
- UWMG model can be provided publicly with a delay of 12 hours, a time resolution every 10 minutes and a spatial resolution of 1x1 degree.









XXVII FIG CONGRESS

Volunteering for the future – Geospatial excellence for a better living

Thank you for your attention!

pawel.wielgosz@uwm.edu.pl

NCN UMO-2017/27/B/ST10/02219







