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# tomated Building Extraction from Dense LIDAR Data

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#### MOTIVATION

- The Earth is becoming more and more anthropogenic.
- Monitting urbanization and urban sprawl is of utmost importance at global, national and local level.
- Agenda 2030 SDGs Towards inclusive and sustainable urbanization.
- One of the ultimate aims in photogrammetry is to generate an urban landscape model to show the objects and land cover of an urban area in 2 or 3D.
- The full automation of extracting buildings has been regarded as an active research topic in digital photogrammetry.











#### Automated Building Extraction from Dense LIDAR Data

- Over the last decade, many research and development efforts have been put into extracting and reconstructing building from images and DEMs data.
- It didn't take long for them to realize the great value in LIDAR data and use LIDAR data in building extraction and reconstruction.
- The high quality of LIDAR data is reflected in three aspects:
  - high accuracy, a typical LIDAR system can provide data with15 cm vertical accuracy and less than 50 cm horizontal accuracy,
  - high consistency of the accuracy, i.e., the accuracy is same everywhere,
  - and **consistency in coverage**, i.e., points are evenly distributed in the covered area.







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#### Automated Building Extraction from Dense LIDAR Data – RESEARCH GOAL

The possibilities and limitations of the Polish spatial data updating by remotely extracted buildings from airborne dense LiDAR data.









## METHOODOLOGY

- Two-stage, top-down, end-to-end methodology of building rooftop outlines extraction.
  - First buildings detection and the approximate building outlines determination.
  - Second geoprocessing to buildings outlines reconstruction, 2D models of the buildings.







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#### **STUDY AREA**

Residential district on the outskirts of Warsaw, diverse building architecture:

- multi-slope roofs,
- dormers and the accompanying vegetation.















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## **DATA USED**

- Dense classified point clouds (12 points per 1 m<sup>2</sup>).
- Buildings data from the Warsaw cadastre.











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## **MODEL PARAMETERS**

Min. building area - 10 m<sup>2</sup>. Near Ground Filter Width - 5 m. The Buildings Points Range - 1.5 m. The Plane Surface Tolerance (PST) – 0.5 m.

95% completeness in comparison with building cadastral data









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## GEOPROCESSING











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## GEOPROCESSING





building the rooftop outline extracted from LAS data



corrected and simplified rooftop outline





shift in building outlines (yellow line) and building footprints from cadastral data (red line)







# XXVII FIG CONGRESS

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## RESULTS



- Roof overhead showed an average shift of 1.18 m (with STD equal to 0.688).
- The dispersion index (VMR) of the shift value (near distance) amounted to 0.4, indicating a binomial distribution (under dispersion).
- Less than 5.6% of the edge points of the building outlines (190 out of 3406) were perceived as outliers, the near distances between corresponding edges in the compared datasets were greater than 2.44 m.









## Automated Building Extraction from Dense LIDAR Data RESULTS







- 28 out of 263 analyzed cadastral buildings contained two outlines derived from LiDAR data processing.
- The highest differences in building area were observed for attached single-family houses.
- The Shape index (SHI) indicates the similarity between cadastral building outlines and LiDAR outline shapes irrespective of their areas.







## Automated Building Extraction from Dense LIDAR Data RECOMENDATIONS

#### Posibilities:

- The automatically extracted building outlines:
  - feed topographic data,
  - be successfully used when planning the cadastral modernization.
- Up-to date information of building location is of high importance in spatial planning and crisis management.

Limitations:

• Roof/ground outline – elaborate reducing algorthm.







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## Thank you for the attention

<u>Further reading</u>: Wierzbicki, D.; Matuk, O.; Bielecka, E. Polish Cadastre Modernization with Remotely Extracted Buildings from High-Resolution Aerial Orthoimagery and Airborne LiDAR. *Remote Sens.* **2021**, 13, 611. <u>https://doi.org/10.3390/rs13040611</u>



